

Local testing of MSC specifications

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Joint work with Puneet Bhateja

DNTTT '08, Cremona, Italy
10 October 2008

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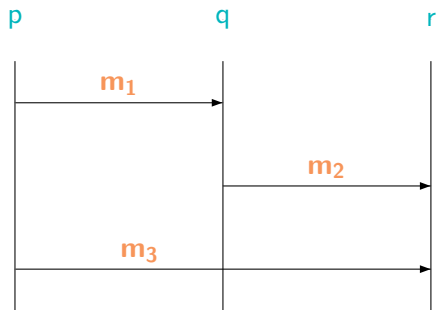
Extends joint work with Paul Gastin, K Narayan Kumar

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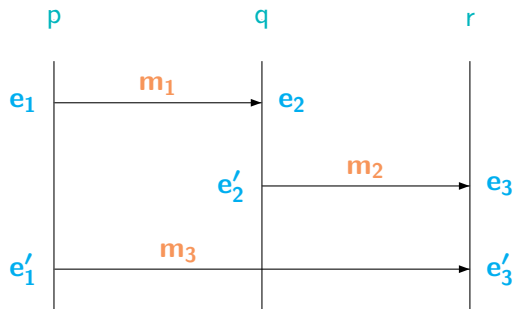
Scenarios

- ▶ Visual specification of message-passing system behaviour
- ▶ A scenario describes a pattern of interaction
- ▶ Telecommunications
 - ▶ Message sequence charts (MSC)
 - ▶ Messages sent between communicating agents
- ▶ UML
 - ▶ Sequence diagrams
 - ▶ Interaction between objects
e.g., method invocations etc

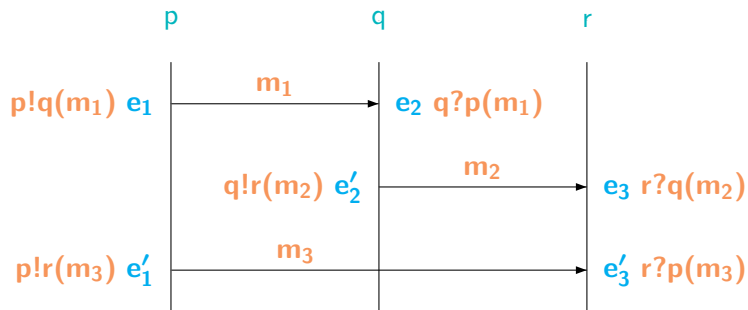
An MSC



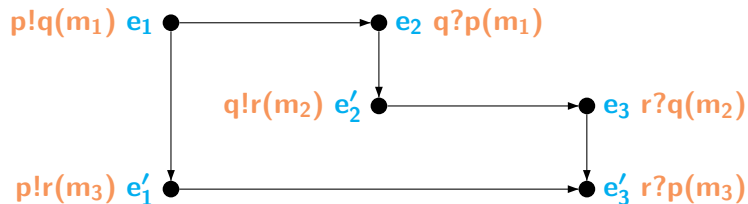
An MSC with events



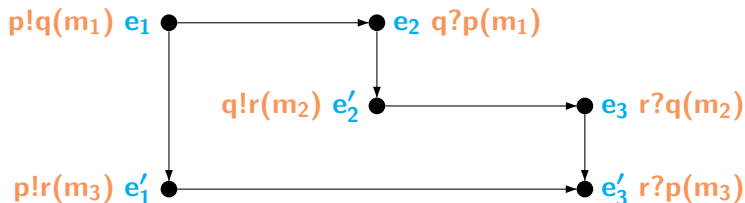
An MSC with events



MSCs as labelled partial orders



MSCs as labelled partial orders



- ▶ Linearizations give a word language
 $p!q(m_1) p!r(m_3) q?p(m_1) q!r(m_2) r?q(m_2) r?p(m_3),$
 $p!q(m_1) q?p(m_1) q!r(m_2) p!r(m_3) r?q(m_2) r?p(m_3), \dots$
- ▶ A single linearization is sufficient to reconstruct MSC

(Local) testing using scenarios

- ▶ Does an implementation conform to an MSC specification?
 - ▶ Are all observed behaviours legal?

(Local) testing using scenarios

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- ▶ Local testing
 - ▶ Selectively monitor the channels of the system
 - ▶ For each process **p**, local observer generates messages for **p** and records the responses
 - ▶ If each local observation is consistent with some MSC in the specification, the implementation passes the test

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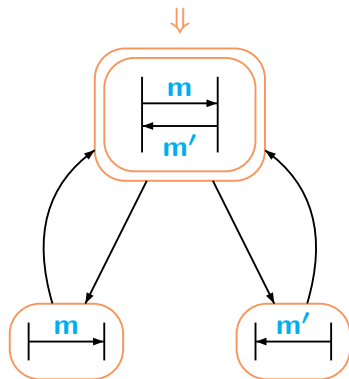
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 - ▶ Selectively monitor the channels of the system
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 - ▶ If each local observation is consistent with some MSC in the specification, the implementation passes the test
- ▶ “Real world” testing—for example, using TTCN-3—is a version of local testing
- ▶ Does local testing suffice to check conformance for (regular) MSC specifications?

High level MSCs (HMSCs) to generate infinite collections

- ▶ A finite state automaton
- ▶ Each state is labelled by an MSC
- ▶ Each (legal) path in the automaton generates an MSC

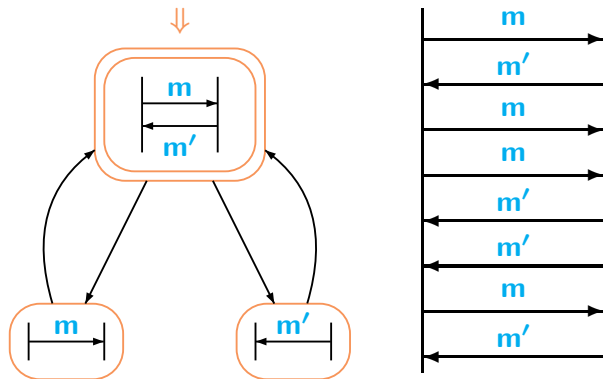
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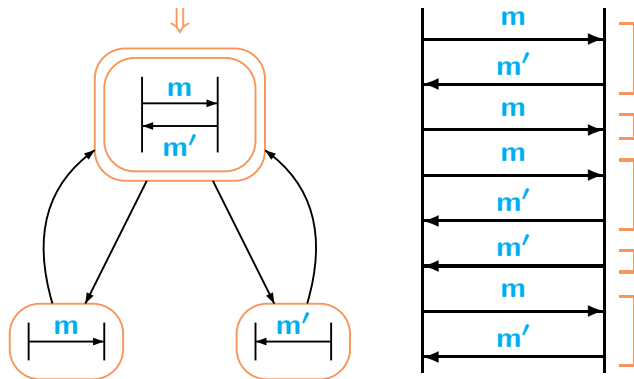
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HMSC semantics

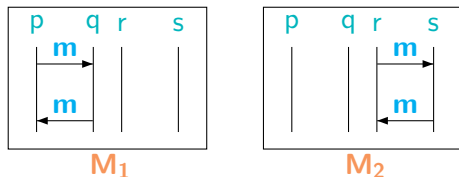
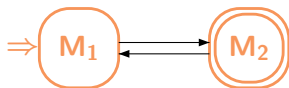
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HMSC semantics

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- ▶ ...but processes move asynchronously
- ▶ Some processes may be (unboundedly) far ahead of others

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- ▶ After **k** iterations, we could have **r** and **s** in the final copy of **M₂** while **p** and **q** are in the first copy of **M₁**

Regular MSC languages

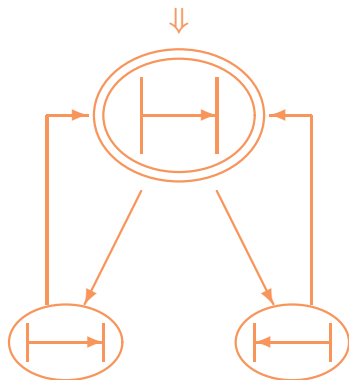
- ▶ An MSC is (uniquely) determined by its linearizations
 - ▶ Set of strings over send actions $p!q(m)$ and receive actions $p?q(m)$
- ▶ Collection of MSCs \Leftrightarrow
word language over send/receive actions
- ▶ Regular collection of MSCs $\stackrel{\Delta}{\equiv}$
linearizations form a regular language

HMSCs and regularity

- ▶ HMSC specifications may not be regular

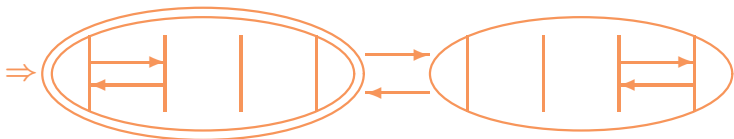
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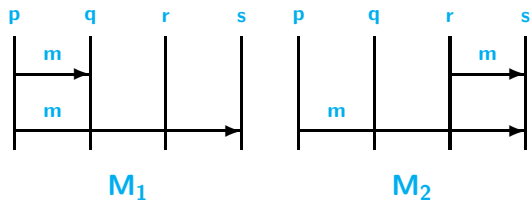
HMSCs and regularity

- ▶ HMSC specifications may not be regular
- ▶ **Problem 1** Unbounded buffers
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- ▶ Sufficient structural conditions on HMSCs to guarantee regularity ... [AY99,MP99]
 - ▶ **Locally synchronized**
- ▶ ... but checking if an HMSC specification is regular is undecidable [HMNST05]

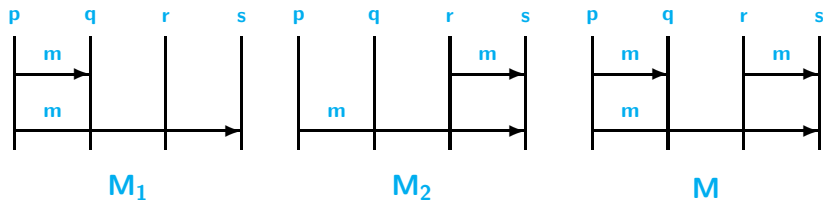
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- ▶ Sufficient structural conditions on HMSCs to guarantee regularity ... [AY99,MP99]
 - ▶ **Locally synchronized**
- ▶ ...but checking if an HMSC specification is regular is undecidable [HMNST05]
- ▶ Every regular MSC language can be implemented as network of communicating finite-state automata with (universally) bounded channels [HMNST05]
- ▶ This channel bound can be computed, if needed.

Implied scenarios [AEY00]

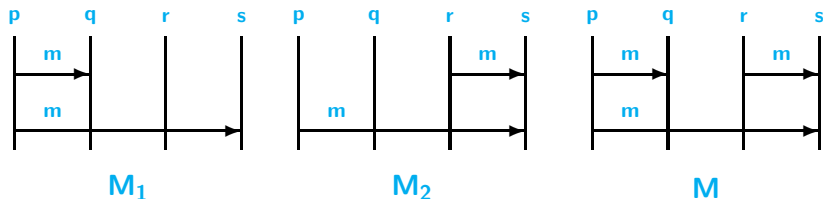


Implied scenarios [AEY00]



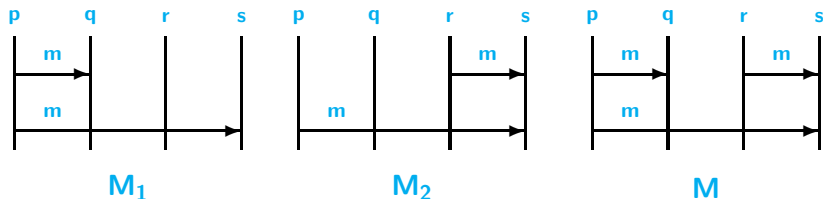
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- ▶ MSC M is implied by L if for each process p , the p -projection of M matches the p -projection of some MSC in L
- ▶ An MSC language is **locally testable** if it is closed with respect to implied MSCs

Implied scenarios . . .

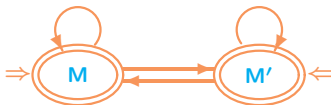
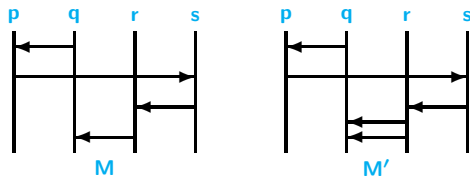
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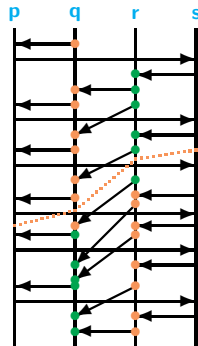
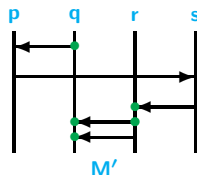
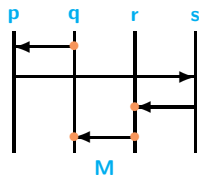
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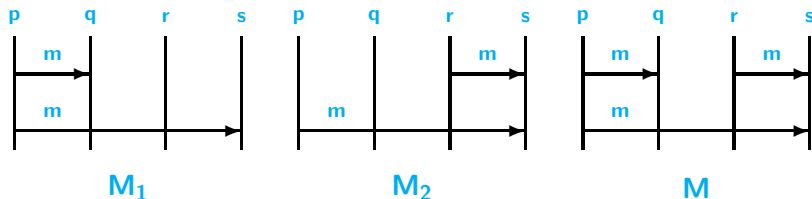
Confusing $M^{2k}M'^k$ and M'^kM^{2k} generates upto k messages in $p \rightarrow s$ channel

Joint observations

- ▶ What if we have observers who can record the behaviours of **sets** of processes?

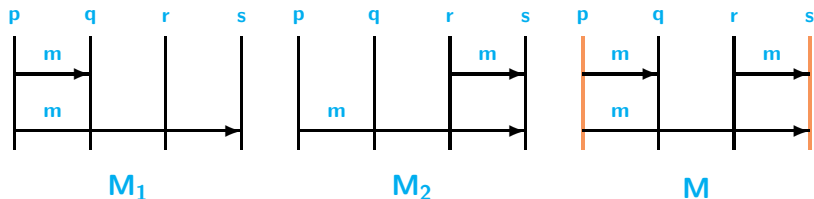
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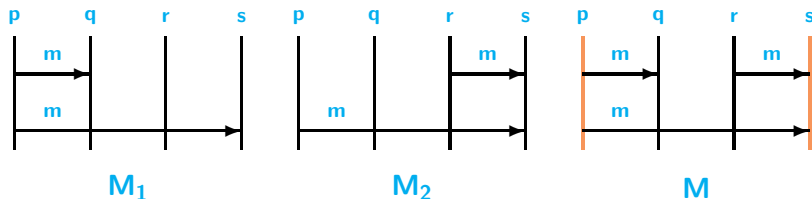
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- ▶ M is detected as an illegal MSC.
- ▶ Joint observers have more discriminating power.
- ▶ The testing model of concurrent TTCN-3 corresponds to local testing with joint observers.

k-testability

- ▶ Record joint observations for every set P of processes of size k .

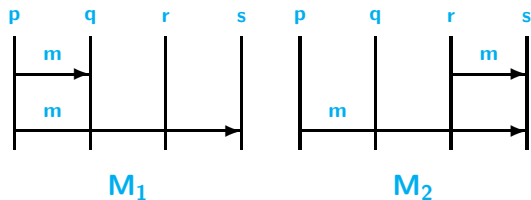
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 $\{M \mid \forall P \text{ s.t. } |P| = k. \exists M' \in L. M \upharpoonright_P = M' \upharpoonright_P\}$
- ▶ **k-implied** scenario M for a language $L \triangleq$
MSC in the **k-closure** of L but not in L

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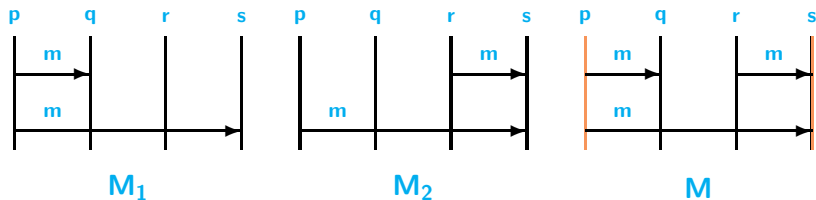
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- ▶ **k-implied** scenario M for a language $L \triangleq$
MSC in the **k-closure** of L but not in L
- ▶ A language is **k-testable** if it equals its **k-closure**
 - ▶ Local testability is **1-testability**

k-testability ...



The set $\{M_1, M_2\}$ is 2-testable but not 1-testable.

k-testability ...



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k-testability ...

- ▶ For all n and $k < n$ there are regular HMSC languages over n processes that are not k -testable
- ▶ 1-testability is undecidable for 4 or more processes. [AEY 01]
- ▶ n -testability is trivially decidable
 - ▶ What about k -testability for $1 < k < n$?
 - ▶ What is the smallest $k \leq n$ such that k -testability is decidable?

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Theorem [BGMN, FCT 2007]

- ▶ k -testability is undecidable for $n \geq 3$ processes and $1 < k < n$
- ▶ 1-testability is undecidable for 2 processes
- ▶ k -testability remains undecidable even with a one-letter alphabet for $n \geq 3$ processes and $1 < k < n$

Local testing with tagging

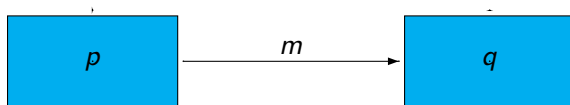
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Local testing with tagging

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- ▶ Embed system within testing layer that tags messages

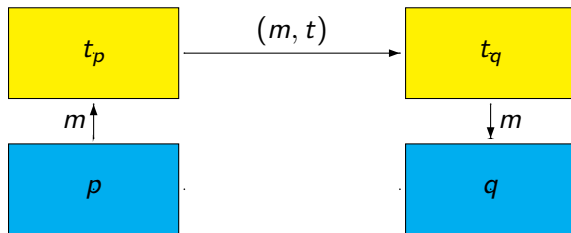
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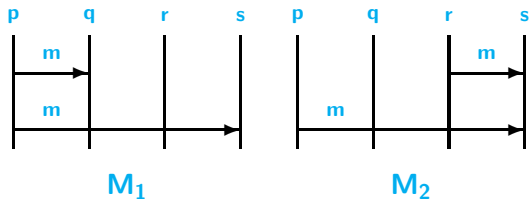
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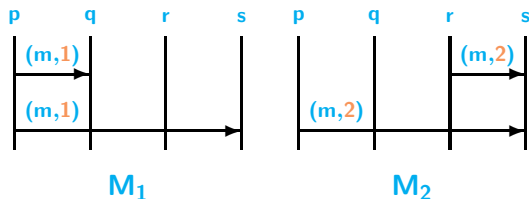


- ▶ Compare local observations of **tagged** system with **tagged** specification

Tagging for local testability ...

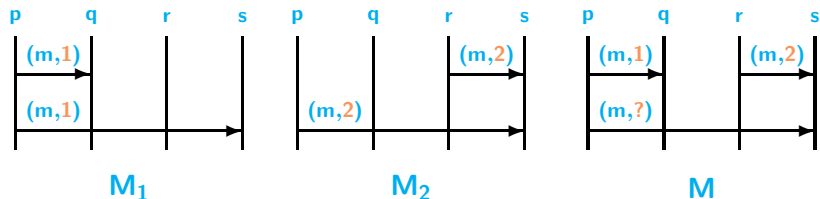


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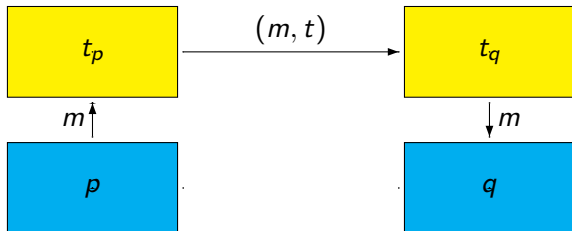
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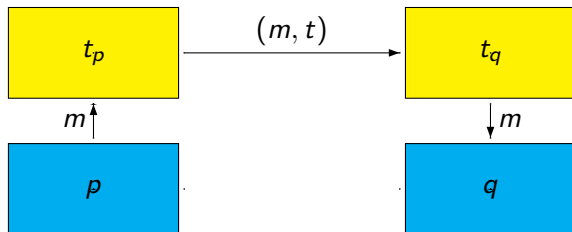


- ▶ By tagging auxiliary information to m in the specification, we know whether the message from p to s comes from M_1 or M_2
- ▶ This rules out the implied scenario M

Implementing tagging

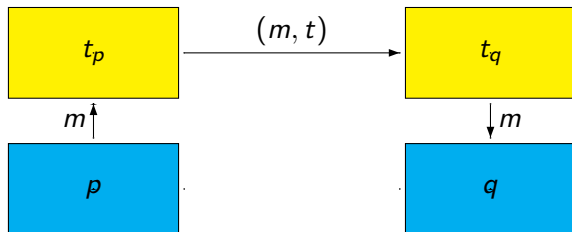


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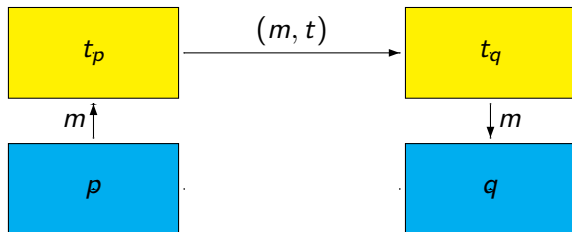
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Implementing tagging



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 - ▶ System under test is **not** modified
 - ▶ Underlying behaviour oblivious to tagging
- ▶ Analogous to compiling with debug flag
 - ▶ Adding debugging information should not modify behaviour of program

Generating tags for local testing

- ▶ How do we generate tags for messages?

Generating tags for local testing

- ▶ How do we generate tags for messages?
- ▶ Bounded timestamping protocol [MNS03]
 - ▶ Each message is assigned a label (timestamp) from a bounded set
 - ▶ Augment messages with auxiliary information
 - ▶ Implicitly records information about size of channels
 - ▶ Includes timestamps of all unacknowledged messages
 - ▶ Message sent by p whose receive event is not in the causal past of p
 - ▶ Ensure that timestamps are reused in a consistent manner
 - ▶ If underlying computation has universally bounded channels, auxiliary information on each message is bounded

Local testing with timestamps

- ▶ Add timestamps to HMSC H to get “unfolded” HMSC H^T
 - ▶ Each node in H^T is a timestamped copy of a node in H
 - ▶ Edges in H^T are consistent with H as well as timestamps
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- ▶ System under test (SUT) is a communicating finite-state machine
 - ▶ Run SUT synchronously with bounded timestamping automaton

$$(q_s, q_t) \xrightarrow{(m,t)} (q'_s, q'_t), \text{ provided}$$

$$q_s \xrightarrow{m} q'_s \text{ (SUT transition), and}$$

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- ▶ Compare timestamped runs of SUT with H^T

H^T and implied scenarios

Theorem

If H is locally synchronized, implied scenarios for H^T have universally bounded channels

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If H is locally synchronized, implied scenarios for H^T have universally bounded channels

- ▶ Implied scenarios have internally consistent timestamps
 - ▶ Timestamping protocol is deterministic
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- ▶ This timestamp cannot be consistent with H^T

H^T and local testability

Corollary

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If H is locally synchronized, then checking whether H^T is locally testable is decidable

- ▶ Project H^T onto each process p
 - ▶ Projections describe a CFM A^T for implied scenarios of H^T
 - ▶ This CFM has universally bounded channels
 - ▶ Implied scenarios of H^T form a regular MSC language

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- ▶ Construct a CFM A from H^T
- ▶ Compare $L(A)$ and $L(A^T)$
 - ▶ Both define regular MSC languages

Connections to realizability

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- ▶ Asynchronous setting : Can cover arbitrary regular MSC specifications exactly using complex timestamping [HMNST05]

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 - ▶ Naively synthesize CFM as product of MSC projections
- ▶ Synchronous setting : Can cover MSC specification with minimum implied scenarios [UKM01]
- ▶ Asynchronous setting : Can cover arbitrary regular MSC specifications exactly using complex timestamping [HMNST05]
- ▶ Tagging can offer an intermediate solution
 - ▶ Synthesize CFM by combining projections modulo tagging
 - ▶ Tagging is deadlock free — will produce a deadlock free implementation if one exists

Connection with causal closure

- ▶ Timestamping approach motivated by work on causal closure of HMSCs [AMNN05]
- ▶ Causal view of a process p of MSC M is set of events causally below maximum p event in M
- ▶ Causally implied MSC — causal view of each process is consistent with some MSC in the language
- ▶ Casual closure of a regular MSC language is regular
 - ▶ Use timestamping to show this, but ...
 - ▶ ... timestamps must be *integrated* into CFM
- ▶ For local testing, timestamping is oblivious to structure of CFM

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- ▶ Can we design more efficient tagging schemes?
 - ▶ For instance, one tag per node in the HMSC
- ▶ Implementation under test is **untagged**
 - ▶ Need to be able to generate tags on the fly while testing

Summary and future work

- ▶ HMSCs — mechanism for specifying collections of scenarios
 - ▶ Attractive visual formalism
 - ▶ Sufficient condition for regularity
- ▶ Local testability is generally undecidable for the original specification
- ▶ Tagging specification with timestamps make local testability decidable
- ▶ What is the “optimal” way to tag a system?
 - ▶ Adding expressiveness increases complexity of testing
- ▶ Can we design more efficient tagging schemes?
 - ▶ Need to generate tags on the fly